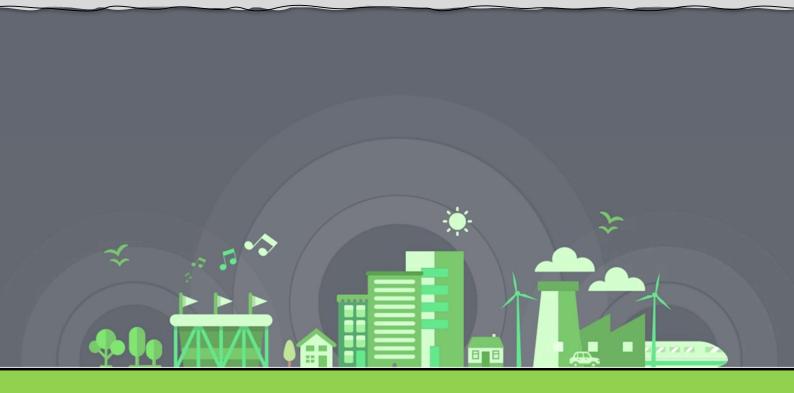
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Noise Impact Assessment of a Proposed Dimension Stone Quarry

Client Name:	A. D. Calvert Care of The Mineral Planning Group Ltd.	
Site Address:	Horn Crag Quarry off Fishbeck Lane, Silsden, West Yorkshire, BD20 0NP	
Date:	05/01/2022	



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Executive Summary

An environmental noise survey and noise impact assessment have been undertaken at Horn Crag Quarry off Fishbeck Lane, Silsden, West Yorkshire, BD20 0NP to assess the potential increase in noise levels from a proposed Dimension Stone Quarry on the surrounding Noise Sensitive Receptors. The measured ambient sound levels have allowed a BS5228:2009 noise assessment to be carried out.

The BS5228:2009 assessment indicates that the noise emissions from the quarry will be a minimum of 7.0 dB below the threshold value calculated using the ABC method. This is within the BS5228:2009 criteria and as such, the impact is classed as 'Not Significant'.

An overview of the recommendations can be found below:

Recommendations and Mitigation Measure Overview

- Stationary plant such as generators should be located as far as possible away from the closest Noise Sensitive Receptor and engines should be turned off whilst idling.
- Plant should be used in accordance with the manufacturers' recommendations.
- Plant which may be used intermittently should be shut down between work periods or throttled down to a minimum.
- Appropriate screens or enclosures should be provided where practicable.
- All plant and machinery should be regularly maintained to control noise emissions, with emphasis on lubrication of bearings and integrity of silencers.
- Use quiet reversing alarms/methods.
- Site staff should be aware that they are working adjacent to residential properties and avoid all unnecessary noise due to misuse of tools and equipment, shouting and radios.
- Adherence to any restrictions of operating hours or activities imposed by the Local Authority.
- Further Recommendations can be found in the body of the report.

The findings of this report will require written approval from the Local Authority prior to work commencing.



1. Introduction

Overview

NOVA Acoustics Ltd has been commissioned to prepare a noise assessment for a proposed Dimension Stone Quarry (the Proposed Development') at Horn Crag Quarry off Fishbeck Lane, Silsden, West Yorkshire, BD20 0NP ('the Site').

The applicant is preparing a planning application to be submitted ('the Application') and has received pre-application advice from the City of Bradford Metropolitan District Council.

The following technical noise assessment has been prepared to support the planning application to the City of Bradford Metropolitan District Council. This report details the existing background sound climate at the nearest receptors, as well as the sound emissions associated with the Proposed Development.

This noise assessment is necessarily technical in nature; therefore, a glossary of terms is included in Appendix A to assist the reader.

Scope & Objectives

The scope of the noise assessment can be summarised as follows:

- Baseline sound monitoring survey to evaluate the prevailing background sound levels at the nearest sensitive receptor ('NSR') to Site;
- Detailed sound modelling, acoustic calculation and analysis in accordance with; ISO9613 1 ISO 9613-2 - Attenuation of sound during propagation outdoors prediction methodology, to predict sound levels at the NSR;
- A detailed assessment of the suitability of the Site, in accordance with relevant standards in respect of sound from the proposed sources; and
- Recommendation of mitigation measures, where necessary, to comply with the requirements
 of the National Planning Policy Framework (2019), Noise Policy Statement for England
 (2010) and British Standard BS5228:2009 'Code of practice for noise and vibration control
 on construction and open sites'. Further information on the legislation can be found in
 Appendix B.

Local Policy Guidance & Discussions with the Local Authority

The following assessment has been requested by the council:

Prediction of anticipated noise levels during the mineral extraction phase must be carried out in accordance with BS 5228: 2009 "Code of practice for noise and vibration control on construction and open sites". Sources of vibration including crushing and other site operations should be included in the noise impact assessment.

- Other legislation controlling noise from mobile plant to be considered includes:
- EC Directive 98/37/EC, The Machinery Safety Directive
- EC Directive 86/662/EC Limitation of noise emitted by hydraulic excavators, rope operated excavators, dozers, loaders and excavator loaders.



The noise impact assessment must also include details of proposed noise and vibration monitoring during the operation of the process appropriate to the activities taking place. Mitigation measures must be included.

If the quarry waste material is to be reworked and re-engineered then there is potential for noise, vibration, dust, odour, lighting and other environmental nuisance to be caused to surrounding properties. The applicant must submit proposals for how such environmental issues will be managed during the mineral extraction works.



2. Environmental Noise Survey

Measurement Methodology

In order to characterise the sound profile of the area at the closest Noise Sensitive Receptor (NSR), an environmental sound survey was carried out from the 19/03/21 to 22/03/21. For the long-term monitoring, a sound level meter was attached to a lamppost approximately 3.5m from the ground. The monitoring position was chosen in order to collect representative sound levels at the NSR during the typical operational periods of the proposed development. The monitoring location is shown in Figure 1.0 below.



Figure 1.0 – Indicative Site Layout

Context & Subjective Impression

The area surrounding the site is primarily pastoral farmland with a minority of residential properties. The noise profile at the NSR is dominated by road traffic noise from Bolton Road and Brown Bank Lane as well as noise from farm animals however these were secondary in nature.

Environmental Noise Survey Results

The proposed quarry will operate 07:30 to 18:00, Monday to Friday, and 08:00 to 13:00 on Saturdays. The table below outlines the lowest ambient sound levels measured during the operational period of the quarry that will be used as the baseline for the noise assessment. Further summary results for the entire measurement period can be found in Appendix D.



Measurement Position MP1				
Measurement Time Period ('t')	L _{Aeq,t}	L _{Amax,t}	L _{A90,t}	LA10,t
Day 1 - 19/03/21 - 08:30 - 18:00	52.0	79.0	49.0	54.0

Table 1.0 – Environmental Survey Summary Results



3. BS5228:2009 Noise Assessment

3.1 On-Site Activities

The activities that are proposed to be undertaken on site are as follows:

- Ripping of rock from quarry faces.
- Splitting of blocks with secondary blasting methods (nonex).
- Loading of blocks onto flatbed trucks.
- HGVs entering and exiting the site to transport materials.
- Stripping of soils to enter next phase (very temporary activity, only occurs for a few weeks per year)
- Landscaping and restoration during the final phase.

The processing of block takes place off-site at an external processing yard.

3.2 Specific Sound Level

The table below shows the noise levels of the equipment which is to be used for the Proposed Development. It is noted that it is unlikely that all plant machinery will be operational simultaneously, and as such, the following assessment is deemed to be a worst-case scenario. The noise data is taken from manufacturers datasheets which can be found in Appendix E.

Description	Sound Pressure Level at 10m (L _{Aeq} , dB)	Sound Power Level (L _{wAr} dB)
Volvo EC480EL Excavator		106.0
Volvo L220H Wheel Loader		109.0
JCB JS130 with Drill Attachment		107.0
McCloskey R155 Screener*	82.0	110.0

Table 2.0 – Plant Equipment Noise Data

*Data taken from McCloskey S130 screener datasheet. The two screeners are assumed to be similar noise levels. The client has stated that the screen will only be used at the start of the development for tasks such as preparing an entrance and turning area. It is estimated that it will be used for a maximum of 6 months.

HGV Movements

The table below shows the noise levels for an HGV entering and leaving the site, taken from BS5228:2009.

Description	L _{wA} (dB)
Lorry Pulling Up	98.0

Table 3.0 – HGV Movement Noise Level



The noise level of the HGVs being loaded/unloaded has also been taken from BS5228:2009. The following table shows the noise level with a time correction applied to account for the loading/unloading process taking approximately 20 minutes per hour.

BS5228:2009	L _{wA} (dB)	Total On-Time	Time Corrected
Process Description		(mins/hour)	L _{wA} (dB)
Lorry Unloading	112.0	20	107.0

Table 4.0 – HGV loading/Unloading Noise Levels

The specific sound levels at the NSRs have been calculated using SoundPlan 8.2, which undertakes its calculations in accordance with the guidance given in ISO9613 – 1:1993 and ISO9613 – 2:1996.

The following assumptions have been made within the calculation software:

- To accurately model the land surrounding the development the topographical data has been taken from Google Maps, it is assumed this has an accuracy within the last 3 years.
 Topographical data for the quarry itself has been provided by the client, this is also included in the model.
- The ground between the source and receiver is a mix of 'soft' and 'hard' surfaces.
- The sound levels presented above have been inputted into the software.
- The HGV movement noise emissions have been modelled as a line source at a height of 1.5m (approximate engine height).
- All operations have been placed in the most exposed areas in relation to the NSRs. This again is considered a worst-case scenario.
- The grid height of the noise map is set to 1.5m.

The sound map showing the specific sound level emissions from the Proposed Development can be seen below in the figure below.

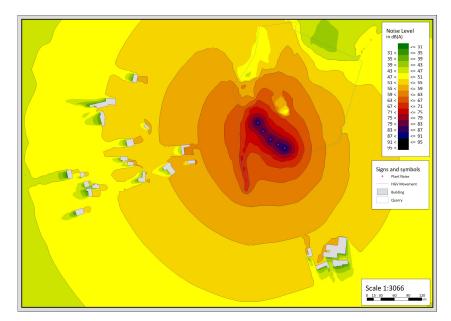


Figure 2.0 – Specific Sound Level Map – 1.5m Grid Height



A summary of the specific sound levels at the NSRs based on the sound map shown in Figure 3.0, can be seen in the following table.

NSR	Specific Sound Level (dBA)
1	58.0
2	54.0

Table 5.0 – Specific Sound Level at NSR Summary

3.3 BS5228:2009-1 Construction Noise Assessment

Based on the measured noise levels shown in Section 2.0, the appropriate threshold values have been determined for the NSRs using the BS5228-1:2009 ABC method. As can be seen in the table below, the lowest L_{Aeq} ambient noise level measured during the weekday operational period was 52.0 dB, and as such, when rounding up to the nearest 5.0 dB the site is considered 'Category A'. This means that a threshold of 65.0 dB is the recommended noise limit level.

The table below shows the predicted noise levels at the most affected NSRs added to the existing ambient noise levels. This is then compared with the threshold level.

ABC Method: Noise Impact Assessment				
Location	Predicted Sound Level (dBA)	Day Time Threshold Level (dB L _{Aeq,12hour})	Significance	
NSR1	58.0	65.0	Not Significant	
NSR2	54.0	65.0	Not Significant	

Table 6.0 – ABC Method: Noise Impact Assessment

Discussion

As can be seen in the assessment above, considering the predicted sound emissions from the proposed activities, no significant impact is expected at the most affected NSRs.

3.4 Recommendations and Mitigation

To reduce the potential impact of noise levels generated by the quarry activities it is recommended mitigation measures be put in place.

In addition, best working practice should be implemented during each phase of the quarry works and close attention should be paid to work within the immediate vicinity of NSRs. The works will follow the guidelines in BS5228-1:2009 and the guidance in BRE Controlling particles, vapour and noise pollution from construction sites, Parts 1 to 5 2003.

The following mitigation measures should be implemented to minimise noise emissions:

• Stationary plant such as generators should be located as far as possible away from the nearest sensitive receptors and engines should be turned off whilst idling.



- Plant should be used in accordance with the manufacturers' recommendations.
- Plant which may be used intermittently should be shut down between work periods or throttled down to a minimum.
- Appropriate screens or enclosures should be provided where practicable.
- All plant and machinery should be regularly maintained to control noise emissions, with emphasis on lubrication of bearings and integrity of silencers.
- Use quiet reversing alarms/methods.
- Site staff should be aware that they are working adjacent to residential properties and avoid all unnecessary noise due to misuse of tools and equipment, shouting and radios.
- Adherence to any restrictions of operating hours or activities imposed by the Local Authority.

If at any time it is necessary to undertake temporary actions that are likely to cause elevated levels of noise, the TCM (or designated responsible person) will contact Environment Health and any other interested parties before such actions are taken to inform them of the operations being undertaken and that the elevated levels of noise will be of a temporary nature. Where practicable, such actions will only proceed when the prevailing wind direction is away from sensitive receptors.

As discussed in the Pre-application advice it may be prudent to undertake noise and vibration monitoring during the mineral extraction phase to ensure the noise and vibration level are not exceeding the relative criteria. Ideally, these noise and vibration monitors would be located in proximity to the closest NSRs. The limit levels that should be adhered to are outlined below.

- Noise 65 dBA as per Category A BS5228-1
- Vibration 0.14 0.3 mm.s⁻¹ PPV as per BS5228-2

3.5 Increase in Ambient Noise Level Assessment

The following section analyses the expected increase in ambient noise levels in the surrounding area due to the Proposed Development. The specific sound levels associated with the Proposed Development are logarithmically added to the lowest measured residual sound level. The higher the increase in noise levels the higher the impact.

Increase in Ambient Noise Level Assessment				
Description	NSR1 (dBA)	NSR2 (dBA)		
Lowest Measured Ambient Noise Level	52.0	52.0		
Specific Noise Level	58.0	54.0		
Resulting Noise Level	59.0	56.1		
Increase in Noise Level	+7.0	+4.1		
Expected Impact	Substantial	Slight/Moderate		

Table 7.0 – Increase in Ambient Noise Level Assessment



Discussion

The results show that the ambient noise levels are predicted to increase by approximately 7.0 dB and 4.1 dB for NSRs 1 and 2 respectively. This is classed as a 'Substantial' impact at NSR1 and 'Slight/Moderate' at NSR2. Whilst this level of impact is high at NSR1, due to the temporary nature of the activities, it is deemed to be acceptable in accordance with BS5228:2009. It should also be noted that the assessment has been undertaken assuming all machinery at the site is operating continuously and simultaneously which is not likely the case. Given this, the impact is likely lower than stated in the IANL Assessment above.



Appendix A – Acoustic Terminology

Sound Pressure	Sound, or sound pressure, is a fluctuation in air pressure over the static ambient pressure.
Sound Pressure Level (Sound Level)	The sound level is the sound pressure relative to a standard reference pressure of 20μ Pa (20×10 -6 Pascals) on a decibel scale.
Decibel (dB)	A scale for comparing the ratios of two quantities, including sound pressure and sound power. The difference in level between two sounds s1 and s2 is given by 20 log10 (s1 / s2). The decibel can also be used to measure absolute quantities by specifying a reference value that fixes one point on the scale. For sound pressure, the reference value is 20μ Pa.
A-weighting, dB(A)	The unit of sound level, weighted according to the A-scale, which takes into account the increased sensitivity of the human ear at some frequencies.
Noise Level Indices	Noise levels usually fluctuate over time, so it is often necessary to consider an average or statistical noise level. This can be done in several ways, so a number of different noise indices have been defined, according to how the averaging or statistics are carried out.
L _{eq,T}	A noise level index called the equivalent continuous noise level over the time period T. This is the level of a notional steady sound that would contain the same amount of sound energy as the actual, possibly fluctuating, sound that was recorded.
L _{max,T}	A noise level index defined as the maximum noise level during the period T. Lmax is sometimes used for the assessment of occasional loud noises, which may have little effect on the overall Leq noise level but will still affect the noise environment. Unless described otherwise, it is measured using the 'fast' sound level meter response.
L _{90,T}	A noise level index. The noise level exceeded for 90% of the time over the period T. L90 can be considered to be the "average minimum" noise level and is often used to describe the background noise.
L _{10,T}	A noise level index. The noise level exceeded for 10% of the time over the period T. L10 can be considered to be the "average maximum" noise level. Generally used to describe road traffic noise.
Free-Field	Far from the presence of sound reflecting objects (except the ground), usually taken to mean at least 3.5m
Facade	At a distance of 1m in front of a large sound reflecting object such as a building façade.
Fast Time Weighting	An averaging time used in sound level meters. Defined in BS 5969.



In order to assist the understanding of acoustic terminology and the relative change in noise, the following background information is provided. The human ear can detect a very wide range of pressure fluctuations, which are perceived as sound. In order to express these fluctuations in a manageable way, a logarithmic scale called the decibel, or dB scale is used. The decibel scale typically ranges from 0 dB (the threshold of hearing) to over 120 dB. An indication of the range of sound levels commonly found in the environment is given in the following table.

Sound Level	Location
0dB(A)	Threshold of hearing
20 to 30dB(A)	Quiet bedroom at night
30 to 40dB(A)	Living room during the day
40 to 50dB(A)	Typical office
50 to 60dB(A)	Inside a car
60 to 70dB(A)	Typical high street
70 to 90dB(A)	Inside factory
100 to 110dB(A)	Burglar alarm at 1m away
110 to 130dB(A)	Jet aircraft on take off
140dB(A)	Threshold of Pain

The ear is less sensitive to some frequencies than to others. The A-weighting scale is used to approximate the frequency response of the ear. Levels weighted using this scale are commonly identified by the notation dB(A).

In accordance with logarithmic addition, combining two sources with equal noise levels would result in an increase of 3 dB(A) in the noise level from a single source. A change of 3 dB(A) is generally regarded as the smallest change in broadband continuous noise which the human ear can detect (although in certain controlled circumstances a change of 1 dB(A) is just perceptible). Therefore, a 2 dB(A) increase would not be normally be perceptible. A 10 dB(A) increase in noise represents a subjective doubling of loudness.

A noise impact on a community is deemed to occur when a new noise is introduced that is out of character with the area, or when a significant increase above the pre-existing ambient noise level occurs.

For levels of noise that vary with time, it is necessary to employ a statistical index that allows for this variation. These statistical indices are expressed as the sound level that is exceeded for a percentage of the time period of interest. In the UK, traffic noise is measured as the L_{A10} , the noise level exceeded for 10% of the measurement period. The L_{A90} is the level exceeded for 90% of the



time and has been adopted to represent the background noise level in the absence of discrete events. An alternative way of assessing the time varying noise levels is to use the equivalent continuous sound level, L_{Aeq} .

This is a notional steady level that would, over a given period of time, deliver the same sound energy as the actual fluctuating sound. To put these quantities into context, where a receiver is predominantly affected by continuous flows of road traffic, a doubling or halving of the flows would result in a just perceptible change of 3 dB, while an increase of more than 25%, or a decrease of more than 20%, in traffic flows represent changes of 1 dB in traffic noise levels (assuming no alteration in the mix of traffic or flow speeds).

Note that the time constant and the period of the noise measurement should be specified. For example, BS4142:2014 specifies background noise measurement periods of 1 hour during the day and 15 minutes during the night. The noise levels are commonly symbolised as $L_{A90,1hour}$ dB and $L_{A90,15mins}$ dB. The noise measurement should be recorded using a 'FAST' time response equivalent to 0.125ms



Appendix B – Legislation, Policy and Guidance

This report is to be primarily based on the following legislation, policy and guidance.

B.1 – National Planning Policy Framework (2019)

Government policy on noise is set out in the National Planning Policy Framework (NPPF), published in 2019. This replaced all earlier guidance on noise and places an emphasis on sustainability. In section 15, Conserving and enhancing the natural and local environment, paragraph 170e, it states:

Preventing new and existing development from contributing to, being put at unacceptable risk from, or being adversely affected by, unacceptable levels of soil, air, water or noise pollution or land instability. Development should, wherever possible, help to improve local environmental conditions such as air and water quality, taking into account relevant information such as river basin management plans;

Paragraph 180 states:

Planning policies and decisions should also ensure that new development is appropriate for its location taking into account the likely effects (including cumulative effects) of pollution on health, living conditions and the natural environment, as well as the potential sensitivity of the site or the wider area to impacts that could arise from the development. In doing so they should:

- a) Mitigate and reduce to a minimum potential adverse impact resulting from noise from new development and avoid noise giving rise to significant adverse impacts on health and the quality of life;
- *b)* Identify and protect tranquil areas which have remained relatively undisturbed by noise and are prized for their recreational and amenity value for this reason; and
- c) Limit the impact of light pollution from artificial light on local amenity, intrinsically dark landscapes and nature conservation.

B.2 – Noise Policy Statement for England (2010)

Paragraph 180 of the NPPF also refers to advice on adverse effects of noise given in the Noise Policy Statement for England (NPSE). This document sets out a policy vision to:

Promote good health and a good quality of life through the effective management of noise within the context of Government policy on sustainable development.

To achieve this vision the Statement identifies the following three aims:

Through the effective management and control of environmental, neighbour and neighbourhood noise within the context of Government policy on sustainable development:

- Avoid significant adverse impacts on health and quality of life;
- Mitigate and minimise adverse impacts on health and quality of life;
- Where possible, contribute to the improvement of health and quality of life.



In achieving these aims the document introduces significance criteria as follows:

SOAEL – Significant Observed Adverse Effect Level

This is the level above which significant adverse effects on health and quality of life occur. It is stated that "significant adverse effects on health and quality of life should be avoided while also considering the guiding principles of sustainable development".

LOAEL – Lowest Observed Adverse Effect Level

This is the level above which adverse effects on health and quality of life can be detected. It is stated that the second aim above lies somewhere between LOAEL and SOAEL and requires that: "all reasonable steps should be taken to mitigate and minimise adverse effects on health and quality of life while also considering the guiding principles of sustainable development. This does not mean that such adverse effects cannot occur."

NOEL – No Observed Effect Level

This is the level below which no effect can be detected. In simple terms, below this level, there is no detectable effect on health and quality of life due to the noise. This can be related to the third aim above, which seeks: "where possible, positively to improve health and quality of life through the pro-active management of noise while also considering the guiding principles of sustainable development, recognising that there will be opportunities for such measures to be taken and that they will deliver potential benefits to society. The protection of quiet places and quiet times as well as the enhancement of the acoustic environment will assist with delivering this aim."

The NPSE recognises that it is not possible to have a single objective noise-based measure that is mandatory and applicable to all sources of noise in all situations and provides no guidance as to how these criteria should be interpreted. It is clear, however, that there is no requirement to achieve noise levels where there are no observable adverse impacts but that reasonable and practicable steps to reduce adverse noise impacts should be taken in the context of sustainable development and ensure a balance between noise sensitive and the need for noise generating developments.

Any scheme of noise mitigation outlined in this report will, therefore, aim to abide by the above principles of the NPPF and NPSE whilst recognizing the constraints of the site.

B.3 – British Standard BS5228 – 1:2009 'Code of practice for noise and vibration control on construction and open sites'

Guidance on the prediction and assessment of noise from development sites is given in BS 5228 – 1:2009 "Code of practice for noise and vibration control on construction and open sites – Part 1 :Noise".

Construction noise can have disturbing effects on the surrounding neighborhood. The effects are varied and are complicated further by the ever changing locations of the site works throughout the construction process. The duration of site operations is also an important consideration. Higher noise levels may be acceptable if it is known that the levels will occur for a limited period. BS5228 -1



provides guidance on significance criteria for assessing the potential noise impact associated with the construction phase of large projects, which would be applicable to construction activities. For the purpose of this noise assessment, the noise likely to be generated during the construction phase have been assessed against the significance criteria established using the BS5228 -1 ABC method.

The ABC method for determining significance criteria requires the ambient noise levels at existing sensitive receptors to be determined. The ambient noise levels at each existing receptor location are then rounded to the nearest 5dB(A) to determine the appropriate threshold value in accordance with the category value, A B or C, as detailed in Table 1.0 below.

Table 1: Thresholds of sign receptors in acc	-	n construction noise BC method of BS522	
Assessment category and threshold value period	Thresh	old value, in decibel	s (dB)
(LAeq)	Category A*1	Category B* ²	Category C* ³
Daytime (0700 to 1900 hours) and Saturdays (0700 to 1300 hours)	65	70	75
Evening and weekends	55	60	56

*1 Category A: Threshold values to use when ambient noise levels (when rounded to the nearest 5dB) are less than this value.

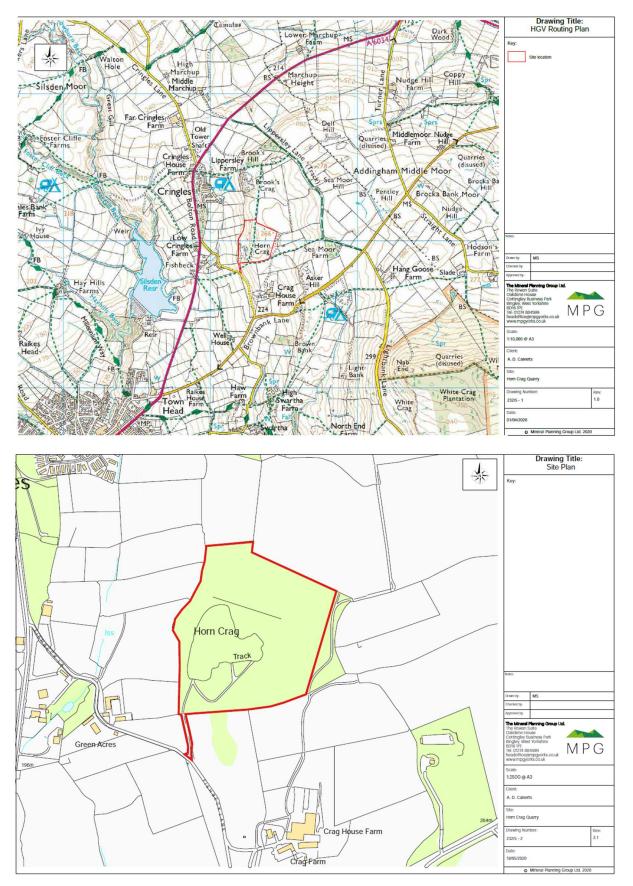
*² Category B: Threshold values to use when ambient noise levels (when rounded to the nearest 5dB) are the same as Category A values.

*³ Category C: Threshold values to use when ambient noise levels (when rounded to the nearest 5dB) are higher than Category A values.

The predicted noise level likely to be generated at the receptor during the construction phase, i.e. the ambient noise level plus construction noise, is then compared to the appropriate category value. If the noise level is greater than the appropriate category value, a significant noise impact may be registered.



Appendix C – Site Plans





Appendix D – Environmental Survey

D.1 – Tabulated Summary Noise Data

Measurement Position MP1	L – Full Mea	surement Su	ummary	
Measurement Time Period ('t')	L _{Aeq,t}	L _{Amax,t}	L _{A90,t}	L _{A10,t}
Friday - 19/03/21 - 08:30 - 23:00	51.0	79.0	43.0	53.0
Friday - 19/03/21 - 23:00 - 07:00	43.0	72.0	35.0	49.0
Saturday - 20/03/21 - 07:00 - 23:00	54.0	79.0	44.0	56.0
Saturday - 20/03/21 - 23:00 - 07:00	44.0	80.0	34.0	47.0
Sunday - 21/03/21 - 07:00 - 23:00	54.0	91.0	43.0	57.0
Sunday - 21/03/21 - 23:00 - 07:00	47.0	78.0	36.0	52.0
Monday - 22/03/21 - 07:00 - 10:10	56.0	77.0	54.0	58.0

Measurement Position MP1	– Operatio	nal Hours S	ummary	
Measurement Time Period ('t')	L _{Aeq,t}	L _{Amax,t}	L _{A90,t}	L _{A10,t}
Friday - 19/03/21 - 08:30 - 18:00	52.0	79.0	49.0	54.0
Saturday - 20/03/21 - 08:00 - 13:00	55.0	78.0	52.0	57.0
Monday - 22/03/21 - 08:00 - 10:10	57.0	77.0	54.0	58.0

Noise Survey Time History

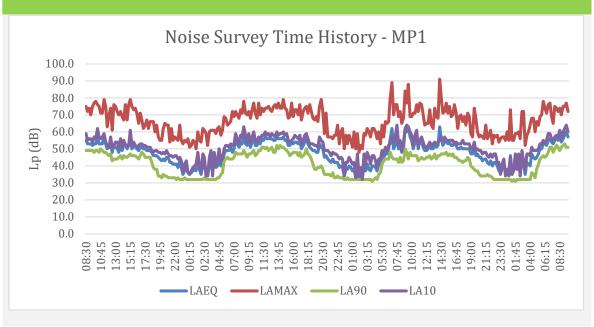


Table 8.0 – Sound Survey Summary Results



D.2 – Surveying Equipment

Piece of Equipment	Serial No.	Calibration Deviation
CESVA SC420 Class 1 Sound Level Meter	T246452	≤0.5
CESVA CB006 Class 1 Calibrator	901997	

Table 9.0 – Measurement Equipment

All equipment used during the survey was field calibrated at the start and end of the measurement period with a negligible deviation of ≤ 0.5 dB. All sound level meters are calibrated every 24 months and all calibrators are calibrated every 12 months, by a third-party calibration laboratory. All microphones were fitted with a protective windshield for the entire measurements period. Calibration certificates can be provided upon request.

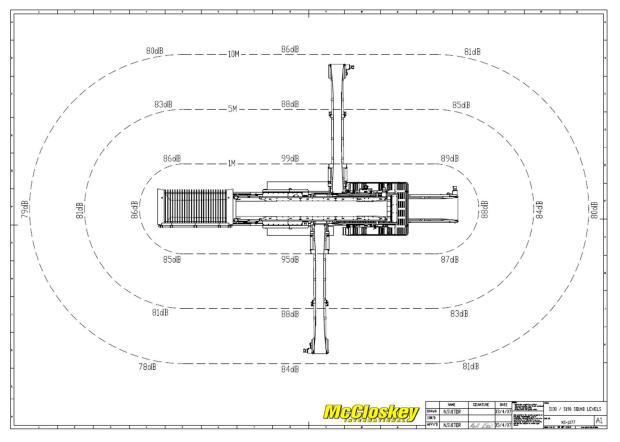
D.3 – Meteorological Conditions

As the environmental noise survey was carried out over a long un-manned period no localized records of weather conditions were taken. However, all measurements have been compared with met office weather data of the area, specifically the closest weather station, and the data from the weather station is outlined in the table below. When reviewing the time history of the noise measurements, any scenarios that were considered potentially to be affected by the local weather conditions have been omitted. The analysis of the noise data includes statistical and percentile analysis and review of minimum and maximum values, which aids in the preclusion of any periods of undesirable weather conditions. The weather conditions were deemed suitable for the measurement of environmental noise in accordance with BS7445 Description and Measurement of Environmental Noise. The table below presents the average temperature, wind speed and rainfall range for each 24-hour period during the entire measurement.

Weather Conditions	6 – Riddlesd	en – 4km S	South-East of Site	
Time Period	Air Temp (°C)	Rainfall (mm/h)	Prevailing Wind Direction	Wind Speed (m/s)
19/03/21 - 00:00 - 23:59	5.9 - 9.9	0.0	ESE	0.0 - 3.9
20/03/21 - 00:00 - 23:59	5.9 - 10.5	0.0	W	0.0 - 5.7
21/03/21 - 00:00 - 23:59	4.2 - 10.7	0.0	SW	0.0 – 2.6
22/03/21 - 00:00 - 23:59	4.1 - 9.9	0.0	W	0.9 - 6.1

Table 10.0 – Weather Summary





Volvo L150H, L180H, L220H in detail

Hydraulic system					Steering System
System supply: Two load-sensi displacement. The steering func Valves: Double-acting 2-spool v Lift function: The valve has four position. Inductive/magnetic auf and off and is adjustable to any j lifting height.	tion alw alve. Th positio tomatic position	ays has prior le main valve ns; raise, hol boom kickou between ma	rity. is electro o d, lower and ut can be sw aximum read	perated. I floating ritched on ch and full	Steering system: System supply: T axial piston pump Steering cylinder
Tilt function: The valve has thre dump. Inductive/magnetic autor					Cylinder bore
bucket angle.			isted to the	desired	Rod diameter
Cylinders: Double-acting cylind Filter: Full flow filtration through	ers for a	all functions.		idao	Stroke
Filter. Full now intracion unougi	110 1110	L150H	L180H	L220H	Working pressure
Working pressure maximum,		LISON	LIOUN	LZZOH	Maximum flow
pump 1 for working hydraulic	MPa	29	29	29	Maximum articula
system					Service Refill
Flow	l/min	180	217	252	Service accessibili
at	MPa	10	10	10	department, elect filters promote lor
engine speed	r/min	1900	1900	1900	tank provides fast
Working pressure maximum, pump 2 for steering-, brake-, pilot- and working hydraulic system	MPa	31	31	31	data to facilitate to
Flow	I/min	202	202	202	DEF/AdBlue® tar
at	MPa	10	10	10	Engine coolant
engine speed	r/min	1900	1900	1900	Hydraulic oil tank
Working pressure maximum,					Transmission oil
pump 3 for brake- and cooling	MPa	25	25	25	Engine oil
fan system					Axle oil front
Flow	l/min	83	83	83	Axle oil rear
at	MPa	10	10	10	Sound Level
engine speed	r/min	1900	1900	1900	
Pilot system, working pressure	MPa	3.5	3.5	3.5	Sound pressure le
Cycle times	_				LpA
Lift	S	5.9	6.4	6.8	External sound les
Tilt	S	2	1.8	1.6	2000/14/EC
Lower, empty	S	3.7	3.3	3.2	LWA
Total cycle time	S	11.6	11.5	11.6	

Steering system: Load-sensi				deensing
System supply: The steering axial piston pump with variab Steering cylinders: Two dou	le displacem	nent.	1 Irom a load	usensing
		L150H	L180H	L220H
Steering cylinders		2	2	2
Cylinder bore	mm	100	100	100
Rod diameter	mm	60	60	60
Stroke	mm	390	525	525
Working pressure	MPa	21	21	21
Maximum flow	l/min	202	202	202
Maximum articulation	±°	37	37	37
Service Refill				
Service accessibility: Large, e department, electrically opera filters promote long service in tank provides faster hydraulic data to facilitate troubleshoot	ted. Fluid fi tervals. A qu oil fill. Poss	Iters and con uick-fit adap	mponent bre ter on the h	eather air /draulic
		L150H	L180H	L220H
Fuel tank	1	L150H 366	L180H 366	L220H 366
		366 31	366 31	366 31
Fuel tank		366 31 55	366	366
Fuel tank DEF/AdBlue® tank		366 31	366 31	366 31
Fuel tank DEF/AdBlue® tank Engine coolant		366 31 55	366 31 55	366 31 55
Fuel tank DEF/AdBlue® tank Engine coolant Hydraulic oil tank		366 31 55 156	366 31 55 156	366 31 55 226
Fuel tank DEF/AdBlue® tank Engine coolant Hydraulic oil tank Transmission oil		366 31 55 156 48	366 31 55 156 48	366 31 55 226 48
Fuel tank DEF/AdBlue® tank Engine coolant Hydraulic oil tank Transmission oil Engine oil Axle oil front Axle oil rear		366 31 55 156 48 50	366 31 55 156 48 50	366 31 55 226 48 50
Fuel tank DEF/AdBlue® tank Engine coolant Hydraulic oil tank Transmission oil Engine oil Axle oil front Axle oil rear		366 31 55 156 48 50 46 55	366 31 55 156 48 50 46 55	366 31 55 226 48 50 77 71
Fuel tank DEF/AdBlue® tank Engine coolant Hydraulic oil tank Transmission oil Engine oil Axle oil front Axle oil rear Sound Level		366 31 55 156 48 50 46 55 L150H	366 31 55 156 48 50 46	366 31 55 226 48 50 77
Fuel tank DEF/AdBlue® tank Engine coolant Hydraulic oil tank Transmission oil Engine oil Axle oil front Axle oil rear		366 31 55 156 48 50 46 55 L150H	366 31 55 156 48 50 46 55 L180H	366 31 55 226 48 50 77 71 L220H
Fuel tank DEF/AdBlue® tank Engine coolant Hydraulic oil tank Transmission oil Engine oil Axle oil front Axle oil rear Sound Level Sound pressure level in cab a L _p A	I I I I I I I I I I I I I I I I I I I	366 31 55 156 48 50 46 55 L150H 1SO 6396 69	366 31 55 156 48 50 46 55 L180H	366 31 55 226 48 50 77 71 L220H
Fuel tank DEF/AdBlue® tank Engine coolant Hydraulic oil tank Transmission oil Engine oil Axle oil front Axle oil rear Sound Level Sound pressure level in cab a	I I I I I I I I I I I I I I I I I I I	366 31 55 156 48 50 46 55 L150H 1SO 6396 69	366 31 55 156 48 50 46 55 L180H	366 31 55 226 48 50 77 71 L220H



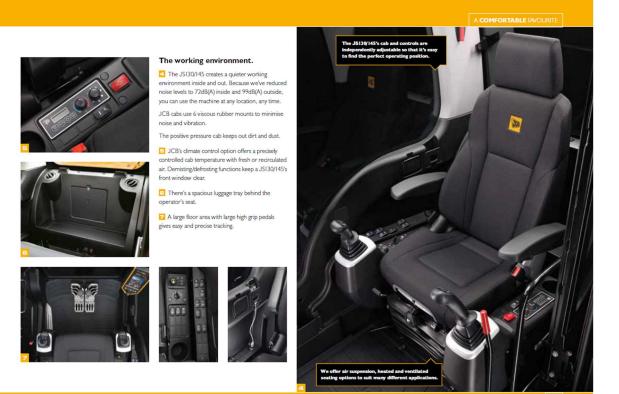
Volvo EC480E in detail

The latest generation, Volvo engine Stage V em	issions certified of	diesel engine fully
meets the demands of the latest, emissions reg	gulations. Featurn	ng Volvo Advanced
Combustion Technology (V-ACT), it is designed and fuel efficiency. The engine uses precise, hig	hpressure fuel ini	ectors, turbo
charger and air-to-air intercooler, and electronic	engine controls	to optimize machine
performance.		
Air Filter: 3-stage with precleaner. Automatic Idling System: Reduces engine spee	ed to idle when th	e levers and pedals
are not activated resulting in less fuel consumpl	tion and low cab	noise levels.
Engine	Volvo	D13J
Max power at	r/min	1800
Net, ISO 9249/SAE J1349	KW	283
	hp	385
Gross, ISO 14396/SAE J1995	kW	284
	hp	386
Maxtorque	Nm	1928
at engine speed	r/min	1350
No. of cylinders		e
Displacement	1	12.8
Bore	mm	131
Stroke	mm	158
Electrical system		
High-capacity electrical system that is we	Il protected. W	aterproof double-
lock harness plugs are used to secure corr	osion-free con	nections. The main
relays and solenoid valves are shielded to switch is standard. Contronics provides an	prevent damag	e. The master
functions and important diagnostic inform	nation.	and a state of the
Voltage	v	24
Batteries	v	2 x 12
Battery capacity	Ah	200
Alternator		
Alternator	V/A	28/80
Swing system	V/A	28/80
Swing system	V/A	28/80
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin	V/A	28/80
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard.	V/A tors, driving a p g brake and an	28/80 blanetary gearbox tirebound valve
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed	V/A tors, driving a p g brake and an r/min	28/80 planetary gearbox tirebound valve 9.3
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque	V/A tors, driving a p g brake and an	28/80 blanetary gearbox tirebound valve
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed	V/A tors, driving a p g brake and an r/min	28/80 planetary gearbox tirebound valve 9.3
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two	V/A tors, driving a p g brake and an r/min kNm o-speed shift tra	28/80 planetary gearbox tirebound valve 9,3 166,3 wel motor. The
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied.	V/A stors, driving a p g brake and an r/min kNm o-speed shift tra and hydraulic re	28/80 planetary gearbox tirebound valve 9.3 166.3 wel motor. The eleased. The travel
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each tracks are multi-disc, spring-applied motor, brake and planetary gears are well p	V/A tors, driving a p g brake and an r/min kNm o-speed shift tra and hydraulic re protected within	28/80 planetary gearbox tirebound valve 9.3 166.3 wel motor. The eleased. The travel the track frame.
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. drawbar pull	V/A tors, driving a p g brake and an r/min kNm o-speed shift tr and hydraulic re wrotected within kN	28/80 slanetary gearbox tirebound valve 9.3 166.3 wel motor. The eleased. The travel the track frame. 333.4
Swing system The swing system uses an axial piston mo for maximum forque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. drawbar pull Max. travel speed (low)	V/A tors, driving a p g brake and an c/min kNm s-speed shift tr and hydraulic re rrotected within kN km/h	28/80 planetary gearbox tirebound valve 9.3 166.3 wel motor. The leased. The travel the track frame. 333.4 3.2
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. drawbar pull Max. travel speed (low) Max. travel speed (logh)	V/A tors, driving a p g brake and an r/min kNm o-speed shift tr and hydraulic re wrotected within kN	28/80 planetary gearbox tirebound valve 9.3 166.3 wel motor. The eleased. The travel the track frame.
Swing system The swing system uses an axial piston mo for maximum forque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. drawbar pull Max. travel speed (low)	V/A tors, driving a p g brake and an c/min kNm s-speed shift tr and hydraulic re rrotected within kN km/h	28/80 planetary gearbox tirebound valve 9.3 166.3 wel motor. The leased. The travel the track frame. 333.4 3.2
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. drawbar pull Max. travel speed (low) Max. travel speed (logh)	V/A tors, driving a p g brake and an c/min kNm s-speed shift tr and hydraulic re rrotected within kN km/h	28/80 planetary gearbox tirebound valve 9.3 166.3 well motor. The teased. The travel the track frame. 333.4 3.2 5.2
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Iravel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. drawbar pull Max. travel speed (low) Max. travel speed (low) Gradeability Undercarriage The undercarriage has a robust X-shaped 1	V/A tors, driving a g g brake and an g/min kNm o-speed shift tra and hydraulic re protected within kN km/h km/h o	28/80 planetary gearbox tirebound valve 9.3 166.3 wel motor. The sleased. The travel the track frame. 333.4 3.1 5.2 38
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. travel speed (low) Max. travel speed (low) Gradeability	V/A tors, driving a g g brake and an g/min kNm o-speed shift tra and hydraulic re protected within kN km/h km/h o	28/80 planetary gearbox tirebound valve 9.3 166.3 wel motor. The sleased. The travel the track frame. 333.4 3.1 5.2 38
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Iravel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. drawbar pull Max. travel speed (low) Max. travel speed (low) Gradeability Undercarriage The undercarriage has a robust X-shaped 1	V/A tors, driving a g g brake and an g/min kNm o-speed shift tra and hydraulic re protected within kN km/h km/h o	28/80 planetary gearbox tirebound valve 9.3 166.3 well motor. The teleased. The travel the track frame. 333.4 5.2 35 35 35 35 35 35 35 35 35 35 35 35 35
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. travel speed (low) Max. travel speed (low) Max. travel speed (high) Gradeability Undercarriage The undercarriage The undercarriage thas a robust X-shaped i chains are standard. Track shoes	V/A tors, driving a g g brake and an g brake and an g brake and m kNm > speed shift tr and hydraulic re rotected within km/h km/h %	28/80 planetary gearbox tirebound valve 9.3 166.3 wel motor. The eleased. The travel the track frame. 333.4 5.2 38 and sealed track 2 x 52
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. drawbar pull Max. travel speed (low) Max. travel speed (low) Gradeability Undercarriage The undercarriage has a robust X-shaped i chains are standard.	V/A tors, driving a g g brake and an g/min kNm o-speed shift tra and hydraulic re protected within kN km/h km/h o	28/80 planetary gearbox tirebound valve 9.3 166.3 wel motor. The eleased. The travel the track frame. 333.4 3.2 5.2 38 and sealed track 2 x 52 215.9 600/ 600HD ⁺ /
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. drawbar pull Max. travel speed (low) The undercarriage The undercarriage has a robust X-shaped t chains are standard. Track shoes Link pitch Shoe width, triple grouser	V/A tors, driving a p g brake and an r/min kNm o-speed shift tr and hydraulic re rotected within km/h km/h km/h o frame. Greased mm mm	28/80 planetary gearbox tirebound valve 9.3 166.3 avel motor. The leased. The travel the travel the travel 15.2 33.4 3.2 5.2 34.3 3.3 4.3 5.2 34.3 3.3 5.2 34.3 3.3 5.2 34.3 35.2 34.3 35.2 34.3 35.2 34.3 35.2 34.3 35.2 34.3 35.2 34.3 35.2 34.3 35.2 34.3 35.2 34.3 35.2 3
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Iravel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. travel speed (low) The undercarriage The undercarriage The undercarriage has a robust X-shaped I chains are standard. Track shoes Link pitch Shoe width, triple grouser Shoe width, double grouser	V/A tors, driving a p g brake and an r/min kNm o-speed shift tr and hydraulic re rotected within km/h km/h km/h o- frame. Greased mm	28/80 clanetary gearbox tirebound valve 9.3 166.3 avel motor. The teased. The travel the track frame. 333.4 3.2 5.2 34 and sealed track 2 x 52 215.9 600/ 600HD+/ 700 / 800/ 900 600
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. travel speed (low) Max. travel speed (low) Max. travel speed (low) Max. travel speed (high) Gradeability Undercarriage The undercarriage The undercarriage Link pitch Shoe width, triple grouser Bottom rollers	V/A tors, driving a p g brake and an r/min kNm o-speed shift tr and hydraulic re rotected within km/h km/h km/h o frame. Greased mm mm	28/80 clanetary gearbox tirebound valve 9.3 166.3 well motor. The tleased. The travel the travel frame. 333.4 3.2 5.2 35 1 and sealed track 2 x 52 215.9 600/ 600HD+/ 700 / 800/ 900 2 x 9
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. travel speed (low) Max. travel speed (low) Gradeability Undercarriage The undercarriage has a robust X-shaped I chains are standard. Track shoes Link pitch Shoe width, triple grouser Bottom rollers Top rollers	V/A tors, driving a p g brake and an r/min kNm o-speed shift tr and hydraulic re rotected within km/h km/h km/h o frame. Greased mm mm	28/80 clanetary gearbox tirebound valve 9.3 166.3 wel motor. The cleased. The travel the track frame. 333.4 3.2 5.2 35 4. and sealed track 2 x 52 215.9 600/ 600HD+/ 700/ 800/ 900 2 x 9 2 x 2 2 x 9 2 x 9 2 x 2 2 x 9 2 x 9 2 x 2 2 x 9 2
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. travel speed (low) Max. travel speed (low) Max. travel speed (low) Max. travel speed (high) Gradeability Undercarriage The undercarriage The undercarriage Link pitch Shoe width, triple grouser Bottom rollers	V/A tors, driving a p g brake and an r/min kNm o-speed shift tr and hydraulic re rotected within km/h km/h km/h o frame. Greased mm mm	28/80 clanetary gearbox tirebound valve 9.3 166.3 well motor. The tleased. The travel the travel frame. 333.4 3.2 5.2 35 1 and sealed track 2 x 52 215.9 600/ 600HD+/ 700 / 800/ 900 2 x 9
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. travel speed (low) Max. travel speed (low) Gradeability Undercarriage The undercarriage has a robust X-shaped I chains are standard. Track shoes Link pitch Shoe width, triple grouser Bottom rollers Top rollers	V/A tors, driving a p g brake and an r/min kNm o-speed shift tr and hydraulic re rotected within km/h km/h km/h o frame. Greased mm mm	28/80 clanetary gearbox tirebound valve 9.3 166.3 wel motor. The cleased. The travel the track frame. 333.4 3.2 5.2 35 4. and sealed track 2 x 52 215.9 600/ 600HD+/ 700/ 800/ 900 2 x 9 2 x 2 2 x 9 2 x 9 2 x 2 2 x 9 2 x 9 2 x 2 2 x 9 2
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. drawbar pull Max. travel speed (low) Max. travel speed (low) Max. travel speed (low) Gradeability Undercarriage The undercarriage has a robust X-shaped t chains are standard. Track shoes Link pitch Shoe width, triple grouser Shoe width, double grouser Bottom rollers Top rollers Top rollers (retractable)	V/A tors, driving a p g brake and an r/min kNm o-speed shift tr and hydraulic re rotected within km/h km/h km/h o frame. Greased mm mm	28/80 clanetary gearbox tirebound valve 9.3 166.3 wel motor. The cleased. The travel the track frame. 333.4 3.2 5.2 35 4. and sealed track 2 x 52 215.9 600/ 600HD+/ 700/ 800/ 900 2 x 9 2 x 2 2 x 9 2 x 9 2 x 2 2 x 9 2 x 9 2 x 2 2 x 9 2
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. drawbar pull Max. travel speed (low) Sndercarriage The undercarriage has a robust X-shaped t chains are standard. Track shoes Link pitch Shoe width, triple grouser Bottom rollers Top rollers Top rollers (retractable) Not HD shoe but HD track link	V/A tors, driving a g g brake and an g brake and an g brake and an k Nm o-speed shift tr and hydraulic r wrotected within km/h km/h ° frame. Greased mm mm	28/80 clanetary gearbox tirebound valve 9.3 166.3 wel motor. The cleased. The travel the track frame. 333.4 3.2 5.2 35 4. and sealed track 2 x 52 215.9 600/ 600HD+/ 700/ 800/ 900 2 x 9 2 x 2 2 x 9 2 x 9 2 x 2 2 x 9 2 x 9 2 x 2 2 x 9 2
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. drawlar pull Max. travel speed (low) Shace track brakes The undercarriage The undercarriage The undercarriage The undercarriage track shaped t chains are standard. Track shoes Link pitch Shoe width, triple grouser Shoe width, double grouser Bottom rollers Top rollers Top rollers Top rollers (retractable) Net HD bace but HD track link Sound Level Sound pressure level in cab according to	V/A tors, driving a g g brake and an g brake and an g brake and an k Nm o-speed shift tr and hydraulic r wrotected within km/h km/h ° frame. Greased mm mm	28/80 clanetary gearbox tirebound valve 9.3 166.3 wel motor. The cleased. The travel the track frame. 333.4 3.2 5.2 35 4. and sealed track 2 x 52 215.9 600/ 600HD+/ 700/ 800/ 900 2 x 9 2 x 2 2 x 9 2 x 9 2 x 2 2 x 9 2 x 9 2 x 2 2 x 9 2
Swing system The swing system uses an axial piston mo for maximum torque. An automatic holdin are standard. Max. slew speed Max. slew torque Travel System Each track is powered by an automatic two track brakes are multi-disc, spring-applied motor, brake and planetary gears are well p Max. drawbar pull Max. travel speed (low) Shae travel speed (low) Max. travel spe	V/A tors, driving a g g brake and an g brake and an c/min kNm c-speed shift tr and hydraulic re rotected within km/h km/h km/h mm mm mm mm mm mm mm	28/80 clanetary gearbox tirebound valve 9.3 166.3 wel motor. The eleased. The travel the track frame. 33.4 5.2 38 and sealed track 2 x 52 215.9 600/ 600HD+// 700 / 800/ 900 2 x 9 2 x 3 2 x 3 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7

The new electro-hydraulic system and new N intelligent technology to control on-demand	Arra (Janeiro	tent of the A
digging capacity and excellent fuel consump	flow for highprotion.	oductivity, high-
The following important functions are includ performance:	ed in the system	n for optimum
performance: Summation system: Combines the flow of b guick cycle times and high productivity.	oth hydraulic p	umps to ensure
Boom priority: Gives priority to the boom op	eration for faste	er raising when
loading or performing deep excavations. Arm priority: Gives priority to the arm operat leveling and for increased bucket filling whe Swing priority: Gives priority to swing functi	tion for faster cy n digging. ons for faster si	vcle times in imultaneous
operations. Regeneration system: Prevents cavitation ar movements during simultaneous operations Power boost: All digging and lifting forces a Holding valves: Boom and arm holding valve	nd provides flow for maximum p re increased.	v to other productivity.
equipment from creeping.	is prevent the t	nggung
Main pump, Type 2 x variable displacement	axial piston pu	imps
Maximum flow	Vmin	2 x 376
Pilot pump, Type Gear pump		
Maximum flow	Vmin	32
Relief value setting pressure		
Implement	MPa	32.4/35.3
Travel circuit	MPa	32.4
Slew circuit	MPa	25.8
Pilot circuit	MPa	3.9
Hydraulic Motors		
Travel: Variable displacement axial piston motor Slew: Fixed displacement axial piston motor		anical brake.
	with mechanic	
	with mechanic	
Hydraulic Cylinders Mono boom	with mechanic	al brake
Hydraulic Cylinders	ø x mm	al brake 2
Hydraulic Cylinders Mono boom		al brake 2 165 x 1 590
Hydraulic Cylinders Mono boom Bore x Stroke		al brake 2 165 x 1 590 1
Hydraulic Cylinders Mono boom Bore x Stroke Arm	ø x mm	
Hydraulic Cylinders Mono boom Bore x Stroke Arm Bore x Stroke	ø x mm	2 2 165 x 1 590 165 x 1 590 190 x 1 850
Hydraulic Cylinders Mono boom Bore x Stroke Arm Bore x Stroke Bucket	ø x mm ø x mm	2 165 x 1 590 165 x 1 590 190 x 1 850 1
Hydraulic Cylinders Mono boom Bore x Stroke Arm Bore x Stroke Bucket Bore x Stroke	ø x mm ø x mm	2 165 x 1 590 165 x 1 590 190 x 1 850 165 x 1 335 165 x 1 335
Hydraulic Cylinders Mono boom Bore x Stroke Arm Bore x Stroke Bucket Bore x Stroke ME Bucket Bore x Stroke	ø x mm ø x mm ø x mm	2 165 x 1 590 165 x 1 590 190 x 1 850 165 x 1 335 165 x 1 335
Hydraulic Cylinders Mono boom Bore x Stroke Arm Bore x Stroke Bucket Bore x Stroke ME Bucket Bore x Stroke	ø x mm ø x mm ø x mm	2 165 x 1 590 1 190 x 1 850 1 165 x 1 335 1 175 x 1 335
Hydraulic Cylinders Mono boom Bore x Stroke Arm Bore x Stroke Bucket Bore x Stroke ME Bucket Bore x Stroke Service Refill	øx mm øx mm øx mm	2 165 x 1 590 190 x 1 850 165 x 1 335 165 x 1 335 175 x 1 335 680
Hydraulic Cylinders Mono boom Bore x Stroke Arm Bore x Stroke Bucket Bore x Stroke ME Bucket Bore x Stroke Service Refill Fuel tank	øx mm øx mm øx mm øx mm	al brake 2 165 x 1 590 190 x 1 850 1 165 x 1 335 1 175 x 1 335 680 62.5
Hydraulic Cylinders Mono boom Bore x Stroke Arm Bore x Stroke Bucket Bore x Stroke ME Bucket Bore x Stroke Service Refill Fuel tank DEF/AdBlue® tank	øx mm øx mm øx mm øx mm	al brake 2 165 x 1 590 190 x 1 850 1 165 x 1 335 1 175 x 1 335 680 62.5 525
Hydraulic Cylinders Mono boom Bore x Stroke Arm Bore x Stroke Bucket Bore x Stroke ME Bucket Bore x Stroke Service Refill Fuel tank DEF/AdBlue® tank Hydraulic system, total	e x mm e x mm e x mm e x mm i i i	al brake 2 165 x 1 590 1 190 x 1 850 1 165 x 1 335 1 175 x 1 335 680 62.5 525 270
Hydraulic Cylinders Mono boom Bore x Stroke Arm Bore x Stroke Bucket Bore x Stroke ME Bucket Bore x Stroke Service Refill Fuel tank DEF/AdBlue® tank Hydraulic system, total Hydraulic tank	exmm exmm exmm exmm i i i i	al brake 2 165 x 1 590 1 190 x 1 850 1 165 x 1 335 175 x 1 335 680 62.5 525 270 42
Hydraulic Cylinders Mono boom Bore x Stroke Arm Bore x Stroke Bucket Bore x Stroke ME Bucket Bore x Stroke Service Refill Fuel tank DEF/AdBlue® tank Hydraulic tank Engine oil	exmm exmm exmm exmm i i i i i i	al brake 2 165 x 1 590 1 190 x 1 850 1 165 x 1 335 680 62.5 525 525 270 42 600
Hydraulic Cylinders Mono boom Bore x Stroke Arm Bore x Stroke Bucket Bore x Stroke ME Bucket Bore x Stroke Service Refill Fuel tank DEF/AdBlue® tank Hydraulic system, total Hydraulic tank Engine oil Engine coolant	8 x mm 8 x mm 8 x mm 8 x mm 1 1 1 1 1 1 1 1	2 165 x 1 590 165 x 1 590 190 x 1 850 1
Hydraulic Cylinders Mono boom Bore x Stroke Arm Bore x Stroke Bucket Bore x Stroke ME Bucket Bore x Stroke Service Refill Fuel tank DEF/AdBlue® tank Hydraulic system, total Hydraulic tank Engine oil Engine colant Slew reduction unit	8 x mm 8 x mm 8 x mm 8 x mm 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	al brake 2 165 x 1 590 1 190 x 1 850 1 165 x 1 335 1 175 x 1 335 680 62.5 525 270 42 60 2 x 6

stored in the side door. Integrated airconditioning and heating system: The pressurized and filtered cab air is supplied by an automaticallycontrolled fan. The air is distributed throughout the cab from 14 vents. Ergonomic operator's seat: The adjustable seat and joystick console move independently to accommodate the operator. The seat has nine different adjustments plus a seat belt for the operator's comfort and safety. Refrigerant of the type R134a is used when this machine is equipped with air conditioning. Contains fluorinated greenhouse gas R134a, Global Warming Potential 1430 CO2-eq.





JSI 30/145 LC/HD TRACKED EXCAVATOR 7